ECD in Riserless operations Methodology in SCA

There are two methods to calculate ECD in riser less drilling, giving two different results. These methods are client specific so we need to check what the client actually wants. This document describes two methods of calculating ECD when no riser is present. It also descirbes how to set up Maxwell software to calculate each method.

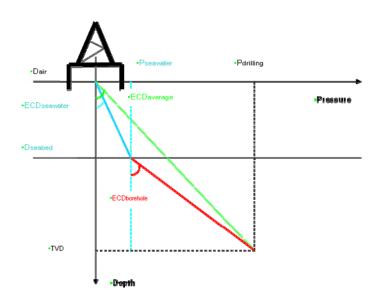


Figure 1. ECD methods in riserless drilling

Method 1: ECD average(See fig 1.)

ECDaverage = Pdrilling

(TVD - Dair)*G

Average Seawater pressure(seawater is constant)

Pdrilling = Annular pressure at sensor

TVD = True vertical depth

Dair = Air gap between Rig floor and mean sea level

G =Constant(0.052 change psi to ppg)

This is the preferred method when Client wants ECD in riserless borehole to relate closely to fracture gradient. This method will give lower relative values of ECD which are less sensitive to changes in borehole but it will fit their model.

Method 1 is the preferred option of Statoil Exploration and Det Norske.

When any client is undertaking exploration it is important to determine which method is preferred

Generally speaking method 1 will compare more closely to client derived fracture gradient of the well.

Before going ahead with riserless drilling where ECD/ESD measurements are required the client must be consulted as to what they would prefer.

Method 2: ECD borehole(See fig 1.)

ECDborehole = Pdrilling — Pseawater

(TVD - Dseabed -Dair)*G

Seawater pressure derived from depth and constant

Pdrilling = Annular pressure at sensor

P_{seawater}= approx 0.44 psi per foot(derived from density of seawater and temperature gradient from surface).

TVD = True vertical depth

Dseabed = Water depth

Dair = Air gap between Rig floor and mean sea level

G = Constant(0.052 change psi to ppg)

This method gives more accurate readings of what is going on at the borehole. As it uses the TVD beginning depth from the seabed it will give higher readings than method one. This method is particularly useful for shallow water flow.

Method 2 has been the preferred option of Shell in Norway but again this has to be double checked

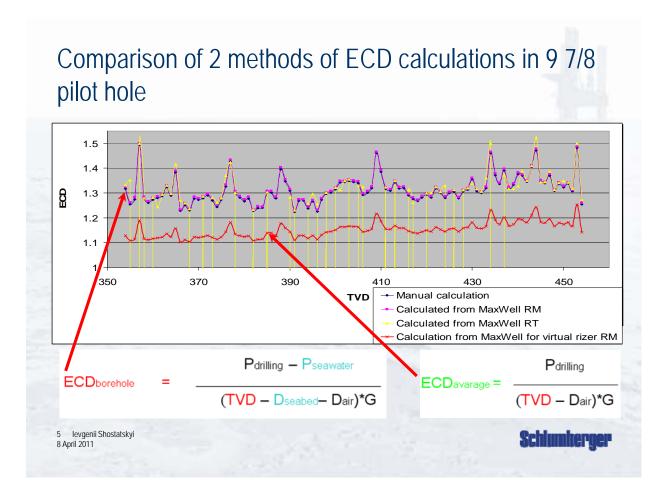


Fig3. Comparison of data from pilot hole ECD calculated with both methods

Comparison of actual data from a rig using both methods shows that ECD calculated with returns to seafloor(top curve fig3) shows that this value is higher and also more sensitive to changes in borehole. The lower curve on figure 3 shows the "average" ECD calculation where seawater pressure is taken to be constant(averaged). These values are lower and less sensitive. These values sit more in line with calculated fracture gradients.

Set up in Maxwell

Method 1: To be used on Statoil Exploration jobs in SCA

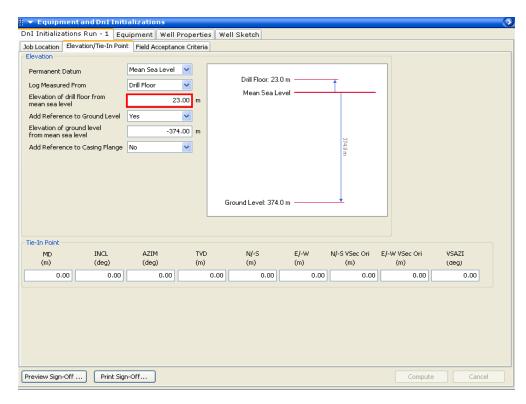


Figure 2. Dnl inits page

Maxwell setup is similar to a normal set up with riser in place.

The DnI initialisations must remain the same as normal



Parameters..

Important things here highlighted are

DFD: Density of seawater=1.03sq

DFT:water

DFT_WATER:Sea water

FLEV: Elevation of Hydraulic Head. This should input the same as the airgap on rig(ADP).

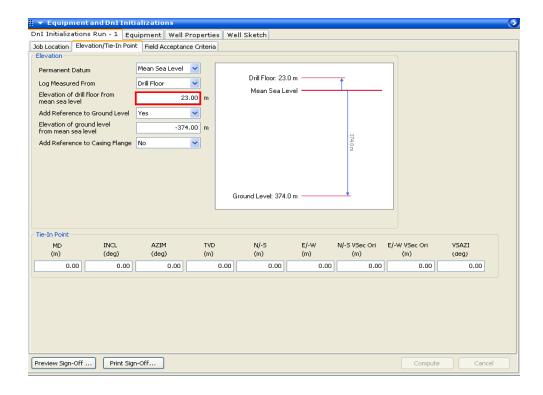
SF_FLAG: Returns to seabed flag should be set to **NO**. This is the difference from the way this has been done before but this fits in with this ECD average model.

FLEV: FLEV under the **SF_FLAG** should be set the same as **ADP**

Essentially Maxwell system thinks that a riser is present and this creates a constant average across seawater which is what we want

Set up in Maxwell

Method 2

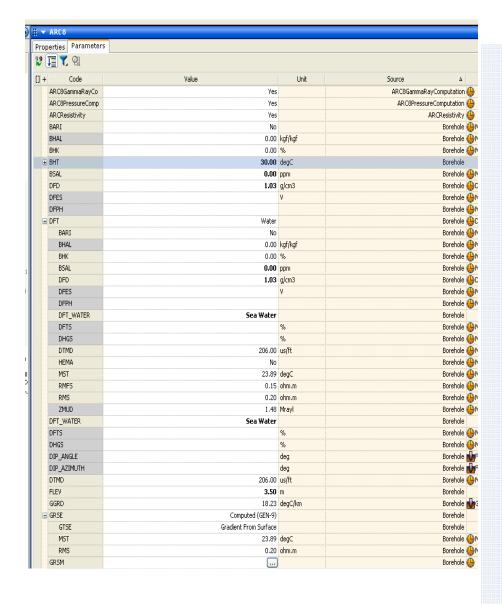


Air GAP(ADP)

This is used in equation in Maxwell to calculate the overburden of seawater

Elevation of ground level(water depth)

This is used in equation to calculate the pressure of sea water at sea bed



■ GTSE	Gradient From Surface 🕶		Borehole
GGRD	18.23	degC/km	Borehole 📆 GG
SHT	10.00	degC	Borehole
GTSM	[]		Borehole 🤒
HEMA	No		Borehole 🤒 M1
■ MST	23.89	degC	Borehole 🕒 M2
BSAL	0.00	ppm	Borehole 🕒 M1
RMB	0.18	ohm.m	Borehole
RHO_SEAWATER	1.03	g/cm3	Borehole
RMB	0.18	ohm.m	Borehole
RMCB		ohm.m	Borehole
RMFB	0.12	ohm.m	Borehole
RMFS	0.15	ohm.m	Borehole 🕒 M2
⊟ RMS	0.20	ohm.m	Borehole 🕒 Mü
BSAL	0.00	ppm	Borehole 🕒 M:
MST	23.89	degC	Borehole 🕒 Ma
RMB	0.18	ohm.m	Borehole
■ SF_FLAG	Yes		Borehole
RHO_SEAWATE	1.03	g/cm3	Borehole
SHT	10.00	degC	Borehole
TD		m	Borehole
ZMUD	1.48	Mrayl	Borehole 🤒 M3

Parameters..

BHT(bottom hole temperature)

Make sure this is reasonably accurate

- not as important in real time as

temperature gradient will be used

DFT(Mud type)

Should be water

DFT_WATER(WBM type)

Should be seawater

GGRD(Geothermal Gradient)

This should be accurate and can be obtained from Drilling program

(note units here are degC per 1000m)

GTSE(Generalized temperature selection)

This is your temperature reference and should be set to gradient from surface

Note: FLEV is not taken into consideration

in this operation -

FLEV is distance between drillfloor and return

flowline, when conductor/riser is present

SHT(surface hole temperature)

This is the reference start point for
temperature gradient. Make sure this is correct
- temperature at seabed

RHO SEAWATER(density of seawater)

This should come from mud report. If no mud report is available then you can use figure of 1.03g/cm3

SF_FLAG(mud return to seafloor)

This should be set to Yes